The Lagrangian capacity of toric domains

Miguel Barbosa Pereira¹

¹Universität Augsburg

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Goal

Basics

Lagrangian capacity

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Conjecture ([Per22, Conjecture 6.24])

If X_{Ω} is a convex or concave toric domain then $c_L(X_{\Omega}) = \delta_{\Omega}$.

Goal

To motivate and prove the conjecture (in some special cases).

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Definition 2.1

The **moment map** is the map $\mu \colon \mathbb{C}^n \longrightarrow \mathbb{R}^n_{\geq 0}$ given by

$$\mu(z_1,\ldots,z_n) \coloneqq \pi(|z_1|^2,\ldots,|z_n|^2).$$

Define also

$$\begin{array}{ll} \Omega_X \coloneqq \Omega(X) \coloneqq & \mu(X) \subset \mathbb{R}^n_{\geq 0}, & \text{for every } X \subset \mathbb{C}^n, \\ X_\Omega \coloneqq X(\Omega) \coloneqq \mu^{-1}(\Omega) \subset \mathbb{C}^n, & \text{for every } \Omega \subset \mathbb{R}^n_{\geq 0}, \\ \delta_\Omega \coloneqq & \delta(\Omega) \coloneqq \sup\{a \mid (a, \dots, a) \in \Omega\}, & \text{for every } \Omega \subset \mathbb{R}^n_{\geq 0}. \end{array}$$

We call δ_{Ω} the **diagonal** of Ω .

Definition 2.2

A **toric domain** is a star-shaped domain X of the form $X = X_{\Omega}$. A toric domain $X = X_{\Omega}$ is

• convex if
$$\hat{\Omega} := \{(x_1, \ldots, x_n) \in \mathbb{R}^n \mid (|x_1|, \ldots, |x_n|) \in \Omega\}$$
 is convex;

• concave if $\mathbb{R}^n_{>0} \setminus \Omega$ is convex.

Example 2.3

The following are toric domains:

$$E(a_1, \dots, a_n) \coloneqq \left\{ z \in \mathbb{C}^n \mid \sum_{j=1}^n \frac{\pi |z_j|^2}{a_j} \le 1 \right\}$$
(ellipsoid)

$$B(a) \coloneqq \left\{ z \in \mathbb{C}^n \mid \sum_{j=1}^n \frac{\pi |z_j|^2}{a} \le 1 \right\}$$
(ball)

$$Z(a) \coloneqq \left\{ z \in \mathbb{C}^n \mid \pi |z_1|^2 \le a \right\}$$
(cylinder)

$$P(a) \coloneqq \left\{ z \in \mathbb{C}^n \mid \forall j = 1, \dots, n \colon \pi |z_j|^2 \le a \right\}$$
(cube)

$$N(a) \coloneqq \left\{ z \in \mathbb{C}^n \mid \exists j = 1, \dots, n \colon \pi |z_j|^2 \le a \right\}$$
(nondisjoint union of cylinders)



Figure: Ball and cube



Figure: Cylinder and nondisjoint union of cylinders

Definition 2.4

A symplectic capacity is a map c which to every symplectic manifold (possibly in a restricted subclass) assigns an element of $[0, +\infty]$, such that

- (Monotonicity) If (X, ω_X) → (Y, ω_Y) is a symplectic embedding of codimension 0 (possibly in a restricted subclass) then c(X, ω_X) ≤ c(Y, ω_Y);
- (Conformality) If $\alpha > 0$ then $c(X, \alpha \omega) = \alpha c(X, \omega)$.

Example 2.5

The cube capacity is given by

$$c_P(X,\omega) \coloneqq \sup\{a \mid \exists \text{ symplectic embedding } P^{2n}(a) \longrightarrow X\}.$$

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Definition 3.1 ([CM18, Section 1.2])

Let (X, ω) be a symplectic manifold. If *L* is a Lagrangian submanifold of *X*, then we define the **minimal symplectic area of** *L* by

$$A_{\min}(L) \coloneqq \inf \{ \omega(\sigma) \mid \sigma \in \pi_2(X, L), \, \omega(\sigma) > 0 \}.$$

Definition 3.2 ([CM18, Section 1.2]) The Lagrangian capacity of (X, ω) is

 $c_L(X) \coloneqq \sup\{A_{\min}(L) \mid L \subset X \text{ is an embedded Lagrangian torus}\}.$

Lemma 3.3 If X is a star-shaped domain, then $c_L(X) \ge c_P(X)$.

Proof.

Let $\iota: P(a) \longrightarrow X$ be a symplectic embedding, for some a > 0. We want to show that $c_L(X) \ge a$. Define $T := \mu^{-1}(a, \ldots, a) \subset \partial P(a)$ and $L := \iota(T) \subset X$. Then, $c_L(X) \ge A_{\min}(L) = A_{\min}(T) = a$. \Box



Figure: Proof of $c_L(X) \ge c_P(X)$ for $X = X_{\Omega}$

Lemma 3.4

If X_{Ω} is a convex or concave toric domain, then $c_P(X_{\Omega}) \geq \delta_{\Omega}$.

Proof.

Since X_{Ω} is convex or concave, we have $P(\delta_{\Omega}) \subset X_{\Omega} \subset N(\delta_{\Omega})$. The result follows since $c_P(X_{\Omega}) := \sup\{a \mid \exists P(a) \hookrightarrow X_{\Omega}\}$. \Box



Figure: If X_{Ω} is convex or concave then $P(\delta_{\Omega}) \subset X_{\Omega} \subset N(\delta_{\Omega})$

We now consider the results by Cieliebak–Mohnke for the Lagrangian capacity of the ball and the cylinder.

Proposition 3.5 ([CM18, Corollary 1.3])

The Lagrangian capacity of the ball is

$$c_L(B^{2n}(1)) = rac{1}{n} = \delta_{\Omega(B^{2n}(1))}.$$

Proposition 3.6 ([CM18, p. 215-216]) The Lagrangian capacity of the cylinder is

$$c_L(Z^{2n}(1)) = 1 = \delta_{\Omega(Z^{2n}(1))}.$$

Conclusion

 X_{Ω} is a convex or concave toric domain $\Longrightarrow c_L(X_{\Omega}) \ge \delta_{\Omega}$ X_{Ω} is the ball or the cylinder $\Longrightarrow c_L(X_{\Omega}) = \delta_{\Omega}$

Conjecture 3.7 ([CM18, Conjecture 1.5]) The Lagrangian capacity of the ellipsoid is

$$c_L(E(a_1,\ldots,a_n))=\left(\frac{1}{a_1}+\cdots+\frac{1}{a_n}\right)^{-1}=\delta_{\Omega(E(a_1,\ldots,a_n))}.$$

Conjecture 3.8 ([Per22, Conjecture 6.24]) If X_{Ω} is a convex or concave toric domain then

$$c_L(X_\Omega)=\delta_\Omega.$$

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Lagrangian capacity

To prove our results about the Conjecture 3.8, we will need to use the following symplectic capacities.

 $\begin{array}{ll} \mathsf{McDuff-Siegel\ capacities} & \widetilde{\mathfrak{g}}_k^{\leq \ell} & [\mathsf{MS22}] \\ \\ \mathsf{Higher\ symplectic\ capacities} & \mathfrak{g}_k^{\leq \ell} & [\mathsf{Sie20}] \\ \\ & \mathsf{Gutt-Hutchings\ capacities} & c_k^{\mathrm{GH}} & [\mathsf{GH18}] \\ \\ \\ \mathsf{for\ } k,\ell\in\mathbb{Z}_{\geq 1}. \text{ We will\ only\ need\ to\ consider\ these\ capacities\ for} \\ \\ \ell=1,\ \mathsf{i.e.\ } \widetilde{\mathfrak{g}}_k^{\leq 1},\mathfrak{g}_k^{\leq 1}. \end{array}$

Theorem 4.1 ([Per22, Theorem 6.40])

If (X, λ) is a Liouville domain and $k \ge 1$ then $c_L(X) \le \tilde{\mathfrak{g}}_k^{\le 1}(X)/k$.

Proof sketch (1/2).

- 1. By definition of c_L , it suffices to assume that $L \subset X$ is an embedded Lagrangian torus and to prove that there exists a disk D with boundary on L with "small" symplectic area.
- 2. By definition of $\tilde{\mathfrak{g}}_k^{\leq 1}$, there exists a sequence u_t of J_t -holomorphic curves with bounded energy and satisfying a tangency constraint.
- 3. By the SFT compactness theorem, u_t converges to a broken holomorphic curve (F_1, \ldots, F_N) (neck stretching along S^*L). Let *C* be the component of the limit which inherits the tangency constraint.

Proof sketch (2/2).

- 4. Since L is a torus, there is an upper bound on the Morse indices of the geodesics in L. Use this together with the SFT index formula to conclude that C must have at least k+1 punctures.
- 5. Therefore, C gives rise to k disks D_1, \ldots, D_k in X with boundary in L. One of these disks is as desired.



Figure: The broken holomorphic curve *F* in the case N = 3

Theorem 4.2 ([Per22, Theorem 6.41]) If X_{Ω} is a 4-dimensional convex toric domain then $c_1(X_{\Omega}) = \delta_{\Omega}$. Proof. For every $k \in \mathbb{Z}_{>1}$, $\delta_{\Omega} \leq c_P(X_{\Omega})$ [by Lemma 3.4] $< c_I(X_{\Omega})$ [by Lemma 3.3] $\leq \tilde{\mathfrak{g}}_{k}^{\leq 1}(X_{\Omega})/k$ [by Theorem 4.1] $= c_{k}^{\mathrm{GH}}(X_{\Omega})/k$ [dim 4 and [MS22, Proposition 5.6.1]] $< c_{k}^{\text{GH}}(N(\delta_{\Omega}))/k$ $[X_{\Omega} \text{ is convex, hence } X_{\Omega} \subset N(\delta_{\Omega})]$ $= \delta_0(k+1)/k$ [by [GH18, Lemma 1.19]].

This finishes the proof of Conjecture 3.8 in the case where X_{Ω} is convex and 4-dimensional. We only used "convex + 4-dimensional" to say that $\tilde{\mathfrak{g}}_k^{\leq 1}(X_{\Omega}) = c_k^{\operatorname{GH}}(X_{\Omega})$. This suggests the following conjecture.

Conjecture 4.3 ([Per22, Conjecture 6.42]) If X is a Liouville domain, $\pi_1(X) = 0$ and $c_1(TX)|_{\pi_2(X)} = 0$, then

$$c_L(X,\lambda) \leq \inf_k rac{c_k^{
m GH}(X,\lambda)}{k}.$$

We will now prove Conjecture 3.8 in full generality, but assuming that there exists a suitable virtual perturbation scheme which defines the curve counts of linearized contact homology. In this case, we can define Siegel's higher symplectic capacities $\mathfrak{g}_k^{\leq 1}$.

Theorem 4.4 ([Per22, Theorem 7.64])

If X is a Liouville domain such that $\pi_1(X) = 0$ and $2c_1(TX) = 0$ then $\mathfrak{g}_k^{\leq 1}(X) = c_k^{\operatorname{GH}}(X)$.

Proof sketch (1/2).

1. Let $E = E(a_1, ..., a_n)$ be a "skinny" ellipsoid such that there exists a strict exact symplectic embedding $\phi: E \longrightarrow X$. Consider the commutative diagram

Proof sketch (2/2).

- 2. By definition of $\mathfrak{g}_k^{\leq 1}$ and c_k^{GH} , we only need to show that ϵ_k^E is an isomorphism, i.e. that the virtual count of curves (asymptotically cylindrical, satisfying a tangency constraint) in the ellipsoid is nonzero.
- 3. For this we show (using automatic transversality techniques) that moduli spaces of asymptotically cylindrical holomorphic curves in ellipsoid are transversely cut out.
- Hence virtual counts agree with "usual" counts. We can count these curves explicitly (they are polynomials) and conclude that the count is nonzero.

Theorem 4.5 ([Per22, Theorem 7.65])

Assume that a suitable virtual perturbation scheme exists. If X_{Ω} is a convex or concave toric domain then $c_L(X_{\Omega}) = \delta_{\Omega}$.

Proof.

$$\begin{split} \delta_{\Omega} &\leq c_{P}(X_{\Omega}) & \text{[by Lemma 3.4]} \\ &\leq c_{L}(X_{\Omega}) & \text{[by Lemma 3.3]} \\ &\leq \tilde{\mathfrak{g}}_{k}^{\leq 1}(X_{\Omega})/k & \text{[by Theorem 4.1]} \\ &\leq \mathfrak{g}_{k}^{\leq 1}(X_{\Omega})/k & \text{[by [MS22, Section 3.4]]} \\ &= c_{k}^{\text{GH}}(X_{\Omega})/k & \text{[by Theorem 4.4]} \\ &\leq c_{k}^{\text{GH}}(N(\delta_{\Omega}))/k & [X_{\Omega} \text{ is convex, hence } X_{\Omega} \subset N(\delta_{\Omega})] \\ &= \delta_{\Omega}(k+n-1)/k & \text{[by [GH18, Lemma 1.19]].} \end{split}$$

$$egin{aligned} c_L(X) &\leq \inf_k rac{ ilde{\mathfrak{g}}_k^{\leq 1}(X)}{k} \ \mathfrak{g}_k^{\leq 1}(X) &= c_k^{\operatorname{GH}}(X) \ c_L(X_\Omega) &= \delta_\Omega \end{aligned}$$

Thank you for listening!

References

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